



From the Front Lines of Open Innovation:  
OpenRelief, OpenStreetMap and Openness Challenges



Planning disaster relief efforts is like trying to see through fog.





OpenRelief is a project to develop better communications tools for disaster relief efforts: the tools to clear the fog.





The idea is to help gather critical information for relief workers on the ground.





Use information to help get the right aid to get to the right place at the right time.





Our first step was to create a robot plane to investigate and map disaster zones.



# Capabilities

- Take off from footpaths.
- Recognize roads, people and smoke.
- Photograph, film and map the landscape.
- Measure weather, radiation and other conditions via modular sensors.

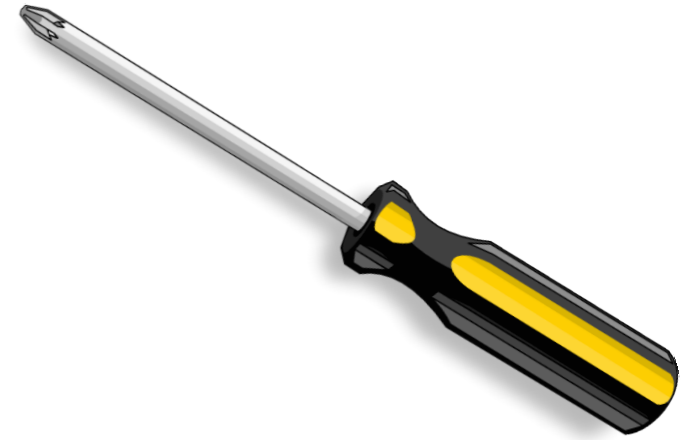


# Seeing Stuff



# How It Was Made

- Many off-the-shelf components.
- Open Hardware computer, autopilot and sensors.
- Free and Open Source Software throughout.



# The System

- Ardupilot Mega to fly the plane.
- Super HAD CDD fisheye camera to see.
- Arduino-based sensors to gather information.
- Raspberry Pi to process data.
- Raspbian OS to analyze the results.



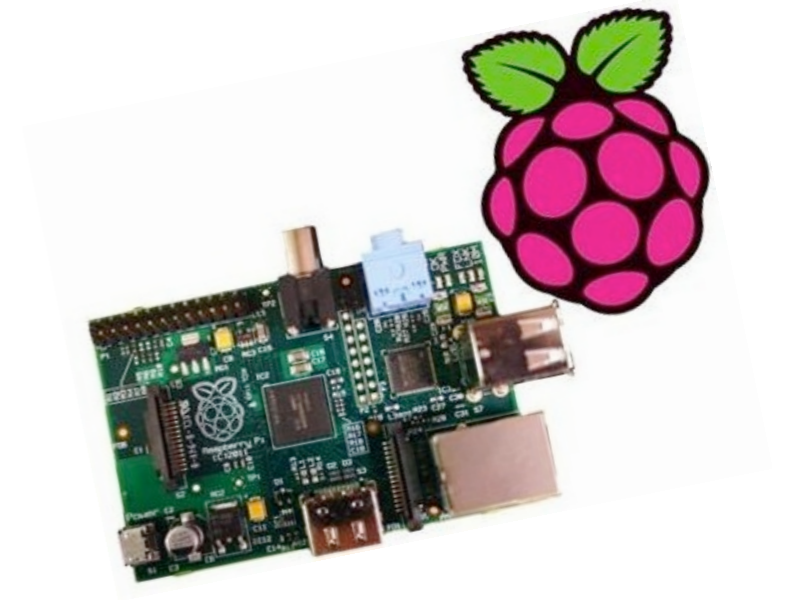
# Autopilot Specs

- 16MHz Atmega2560 processor.
- 256k Flash Program Memory, 8K SRAM, 4K EEPROM.
- 600 3D waypoints and mission commands.
- 16MB Data Logger (Black Box).
- Can reboot the processor in mid-flight.



# Computer Specs

- BCM2835 700 MHz ARM11
- 256-MB LPDDR RAM.
- 1080p30 H.264 encode/decode, HDMI.
- GPIO pins, Serial Bus (SPI), UART and 10/100 wired Ethernet RJ45.
- SD / MMC / SDIO card support.



# Software Specs

- ArduPlane 2.32 (autopilot).
- Debian 6 (OS).
- OpenCV 2.3.1 (visual recognition).
- Custom code for smoke, people, roads and SfM (structure from motion).

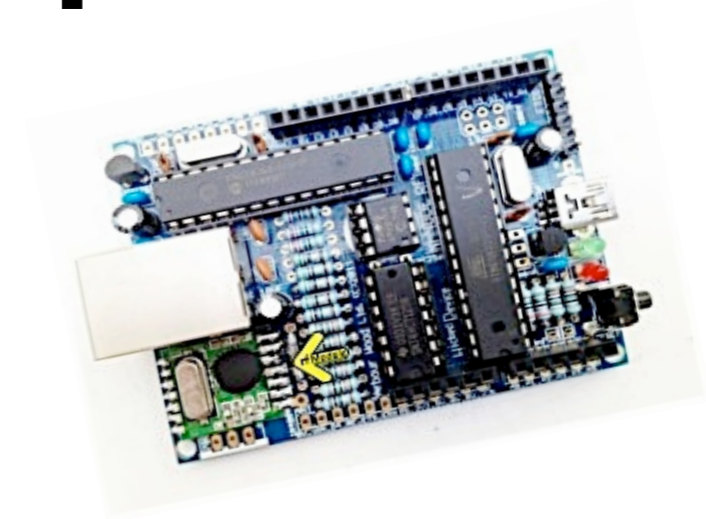


# Camera Module Specs

- Sensor: 1/3" Sony Super HAD ii CCD
- Lens: 1.78mm | 70 degree view angle.
- Minimum Light: 0.1 Lux at F1.2.
- Auto Tracking White Balance.
- Operating Temp.: -10°C ~ +50°C

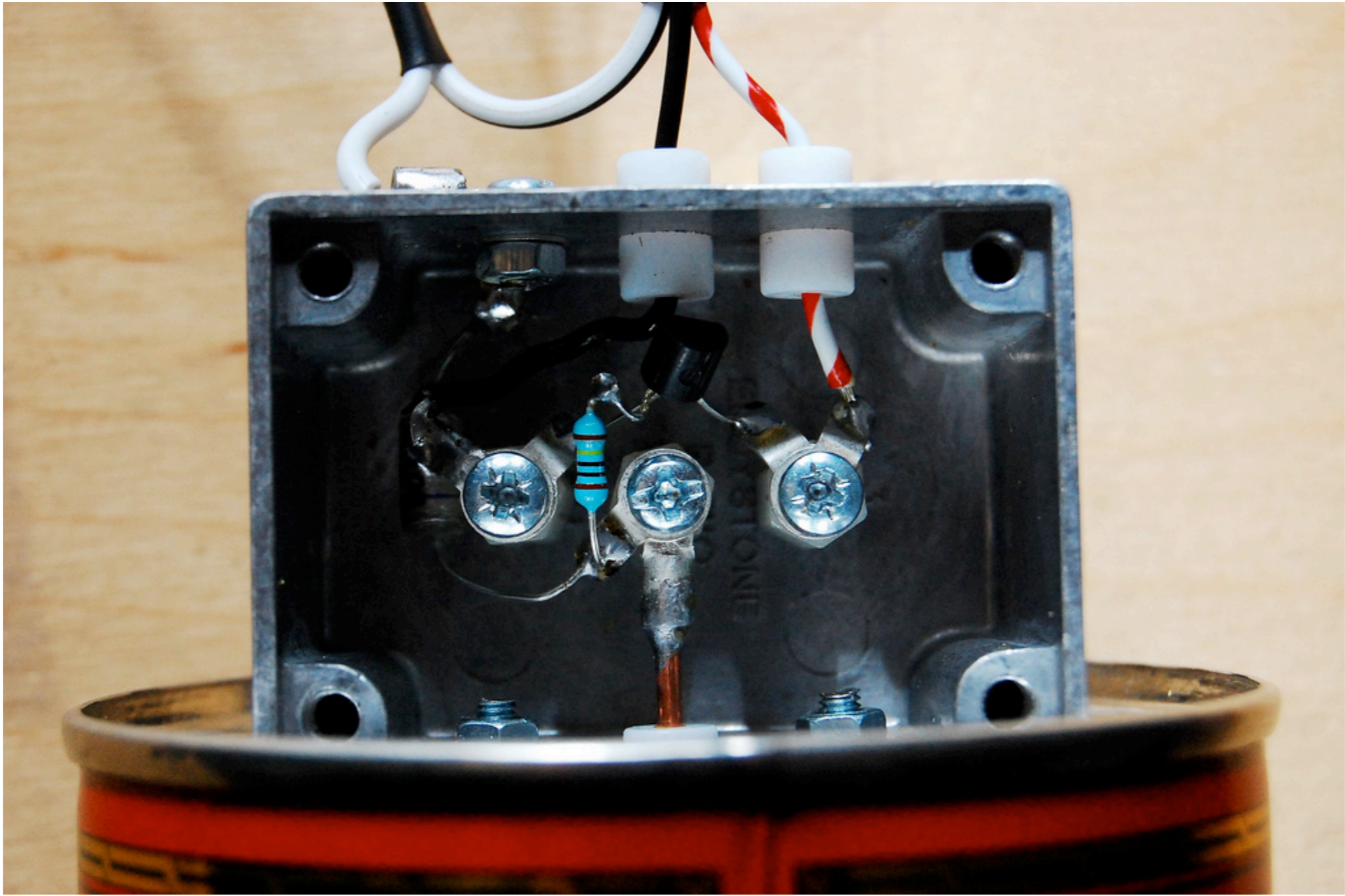


# Radiation Module Specs



- Nanode RF:
  - ATmega328p 8-bit RISC microprocessor.
  - RFM12B radio module (100 meter range).
- Custom Ionization chamber or J305 $\beta$  Geiger Tube.





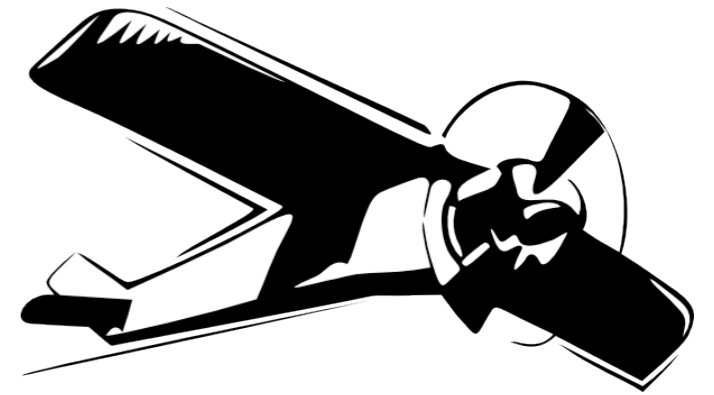
# Mission Control

- Laptop with a USB connection.
- Debian 6, Ubuntu 11/10 or Windows.
- Mission Planner 1.1.89.
- VLC Player 2.0.1.
- Disaster management software at HQ  
(Sahana Eden or similar)



# Test Airframe

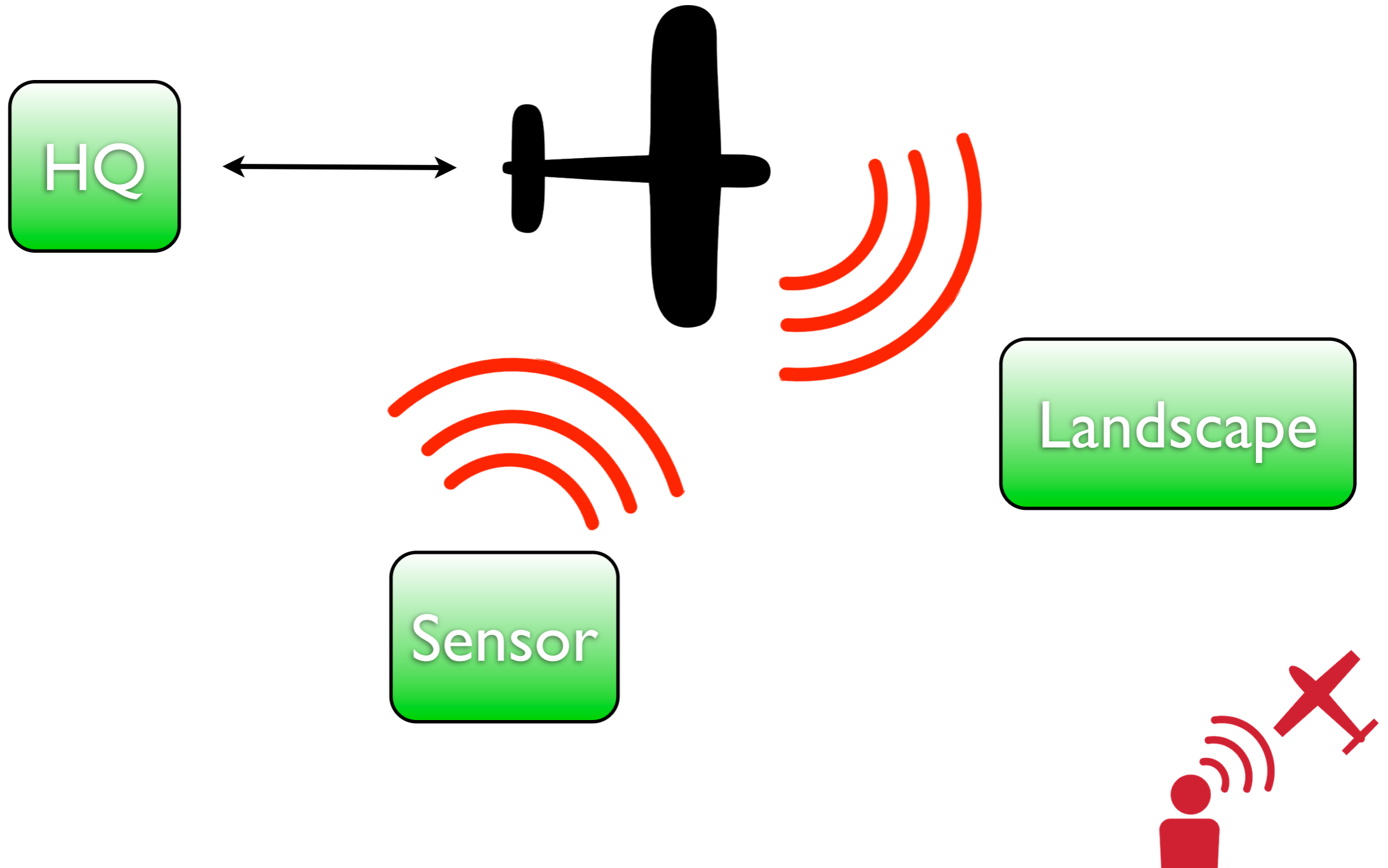
- Body: Fiberglass and balsa wood.
- Wing Span: 1660mm.
- Fuselage: 1190mm.
- Weight: 2 - 3kg.
- 20 - 30 minutes endurance.



# A Little Eco-System



# Putting It All Together

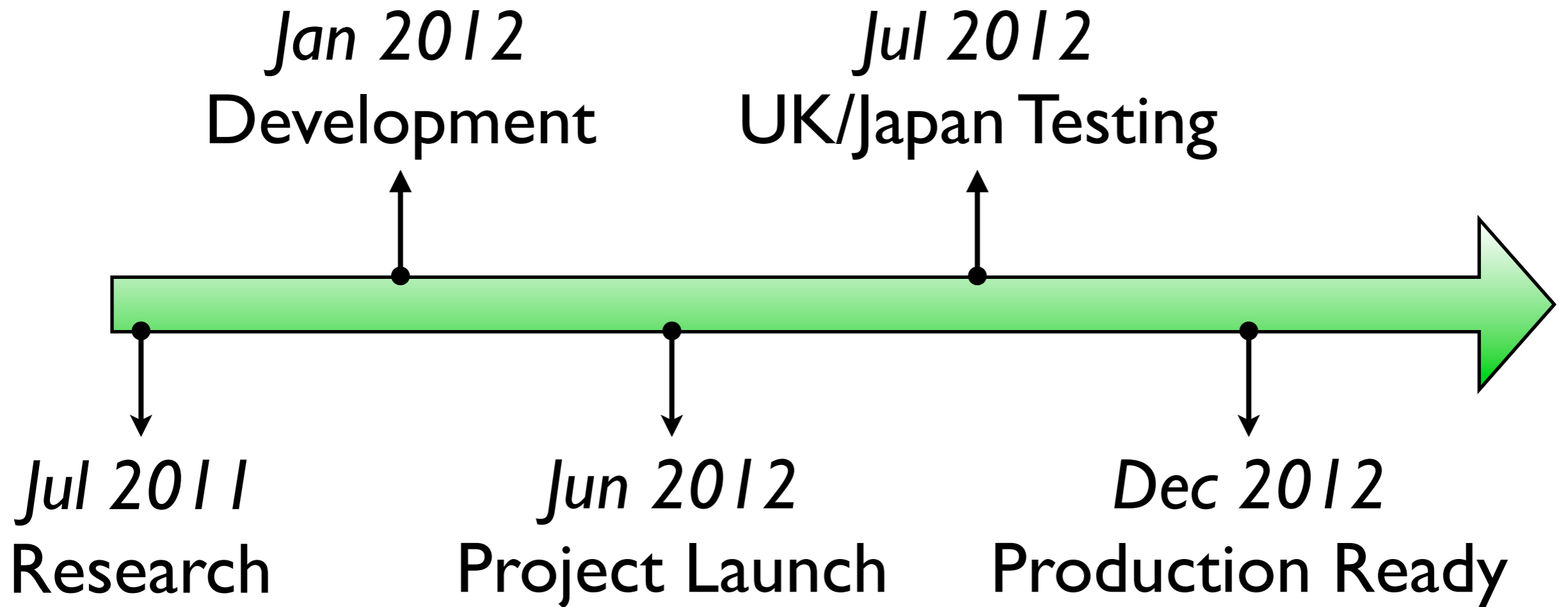


# Potential vs Reality

- The software is quick to hack, but a lot of it requires specialists to improve.
- The airframes nearly always suck.
- Integration of all the software and hardware is a significant challenge.



# Milestones





OpenRelief is part of a global community to develop solutions around the world.



# Global Improvement

- CanberraUAV has created excellent UAV tools for flight and imaging.
- OpenRelief was approached by an aviation specialist to release a capable, open airframe.
- We are building relationships with emergency responders and universities to further integration.





Take two - getting a cool airframe out there





It's the little things



# Be Part Of This

- Visit [www.openrelief.org](http://www.openrelief.org)
- Join our user list to get up to speed.
- Join our developer list to work on tools.
- Join our outreach list to help spread the word.



# Get Our Tools

- You will find test code at:  
[www.gitorious.org/OpenRelief](http://www.gitorious.org/OpenRelief)
- You will find device schematics at:  
[www.solderpad.com/OpenRelief](http://www.solderpad.com/OpenRelief)



# Thank You!



Oldham College

